



Cornell Mars Rover

Greetings
Earthlings!

Recruitment 2015-2016

DESIGN, BUILD, AND OPERATE
a mock rover that can perform

a variety of *field*
tasks to assist in

A FUTURE MISSION TO
MARS



We're Young & Hip

544

Years

Members

Rovers

as an
established team

with diverse
backgrounds

built with
love and care



Eos (2012)



Helios (2013)



Ares [2014]



Garcia [2015]



We're Looking For

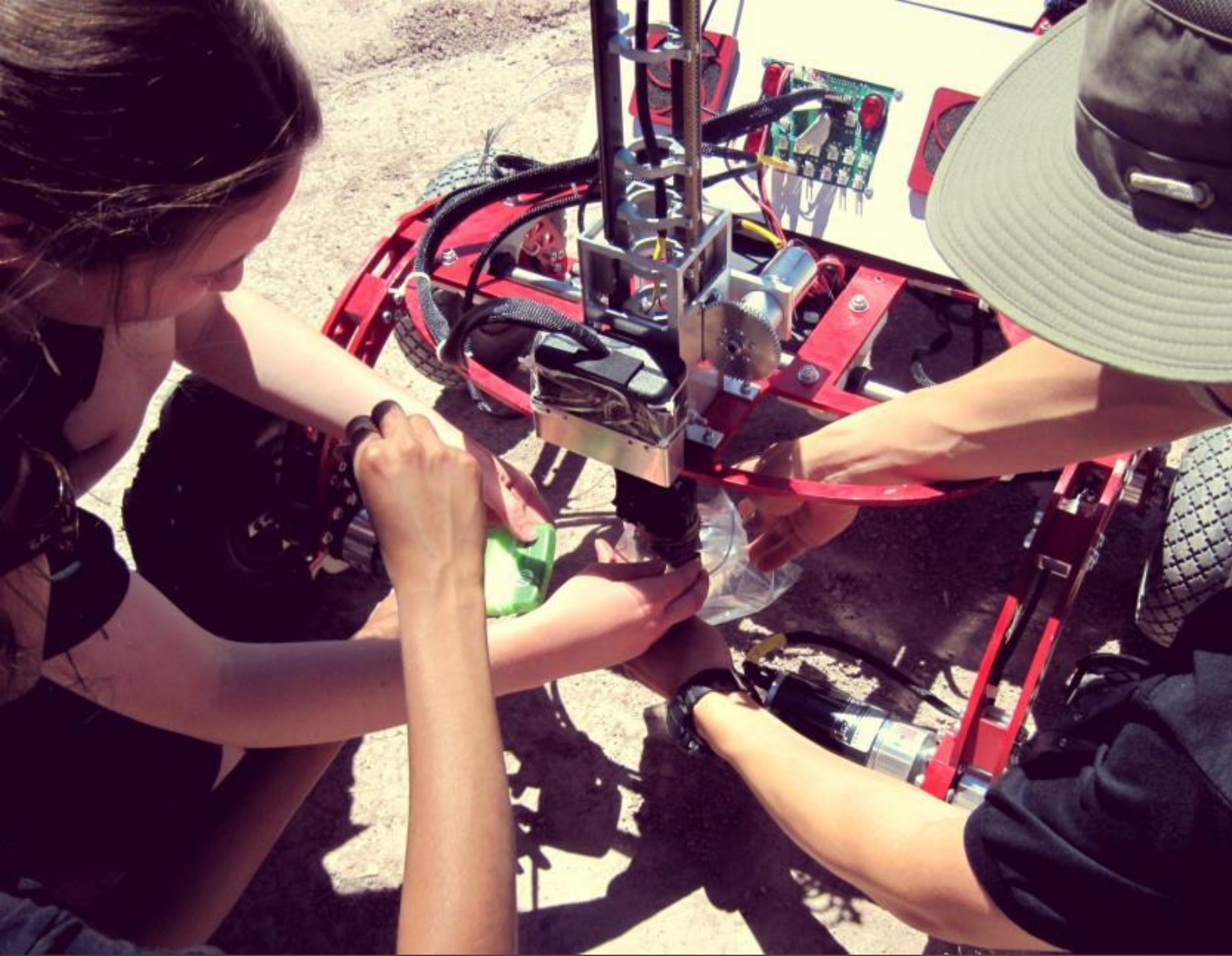
Creative Problem Solvers

University Rover Challenge

Occurs each year at the end of **May**

Compete against over **40 International Teams**

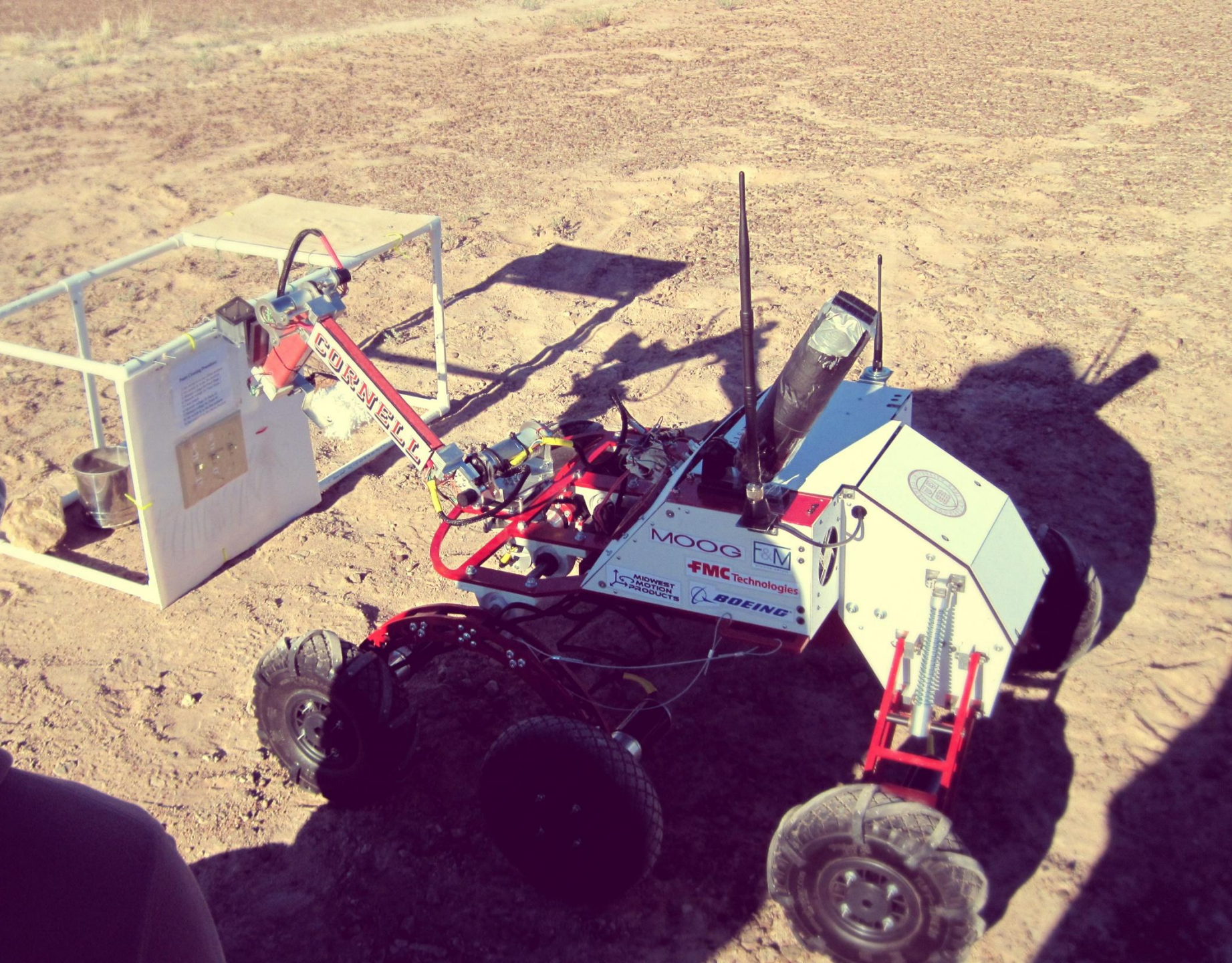
Winners: Opportunity to present at International Mars Society Convention



1

URC Task

Soil Sample
Analysis



2

URC Task

Equipment
Servicing





3

URC Task

Astronaut
Assistance





4 URC Task

Terrain
Traversal



Research

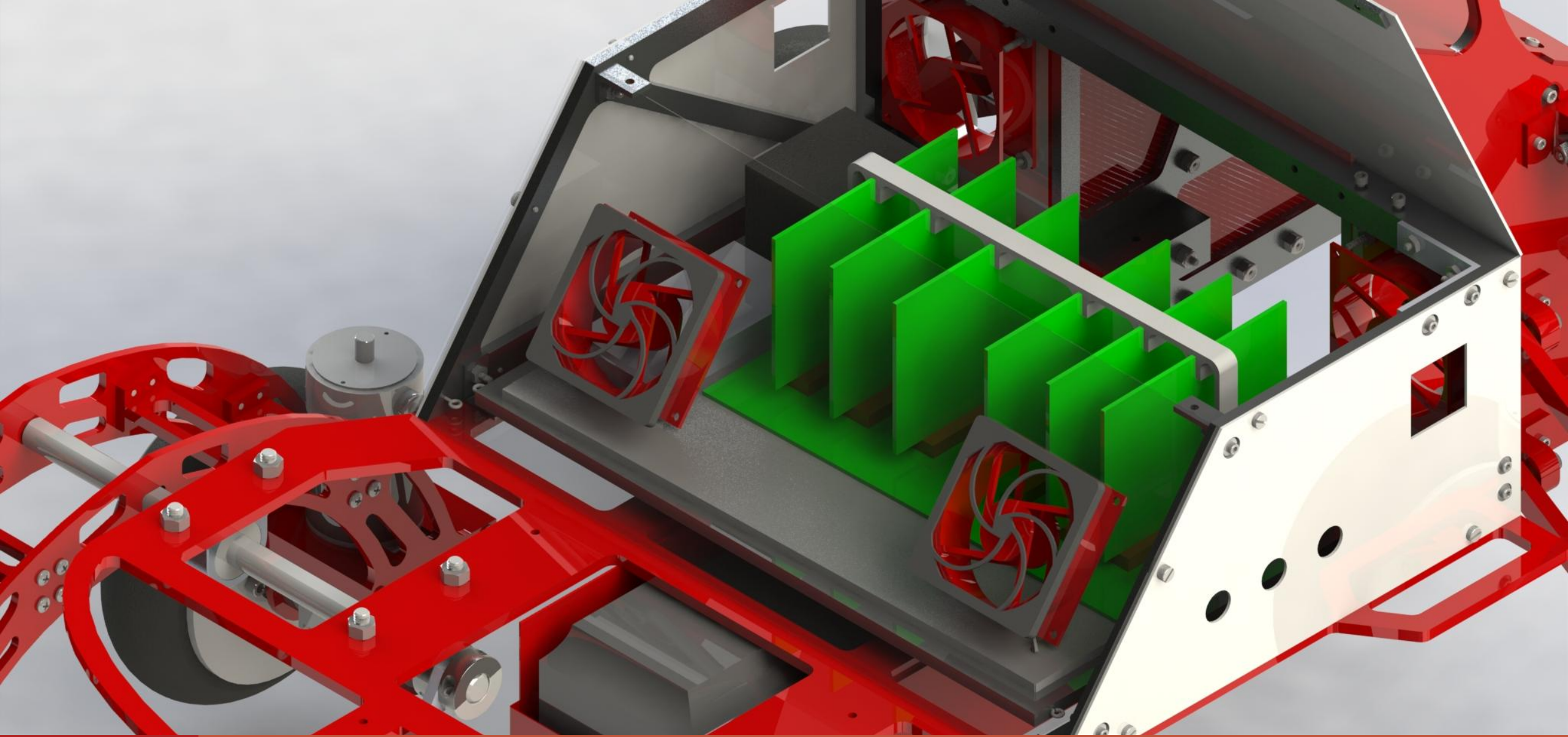


Build



Test

August – November



Computer Aided Design & Analysis



Research

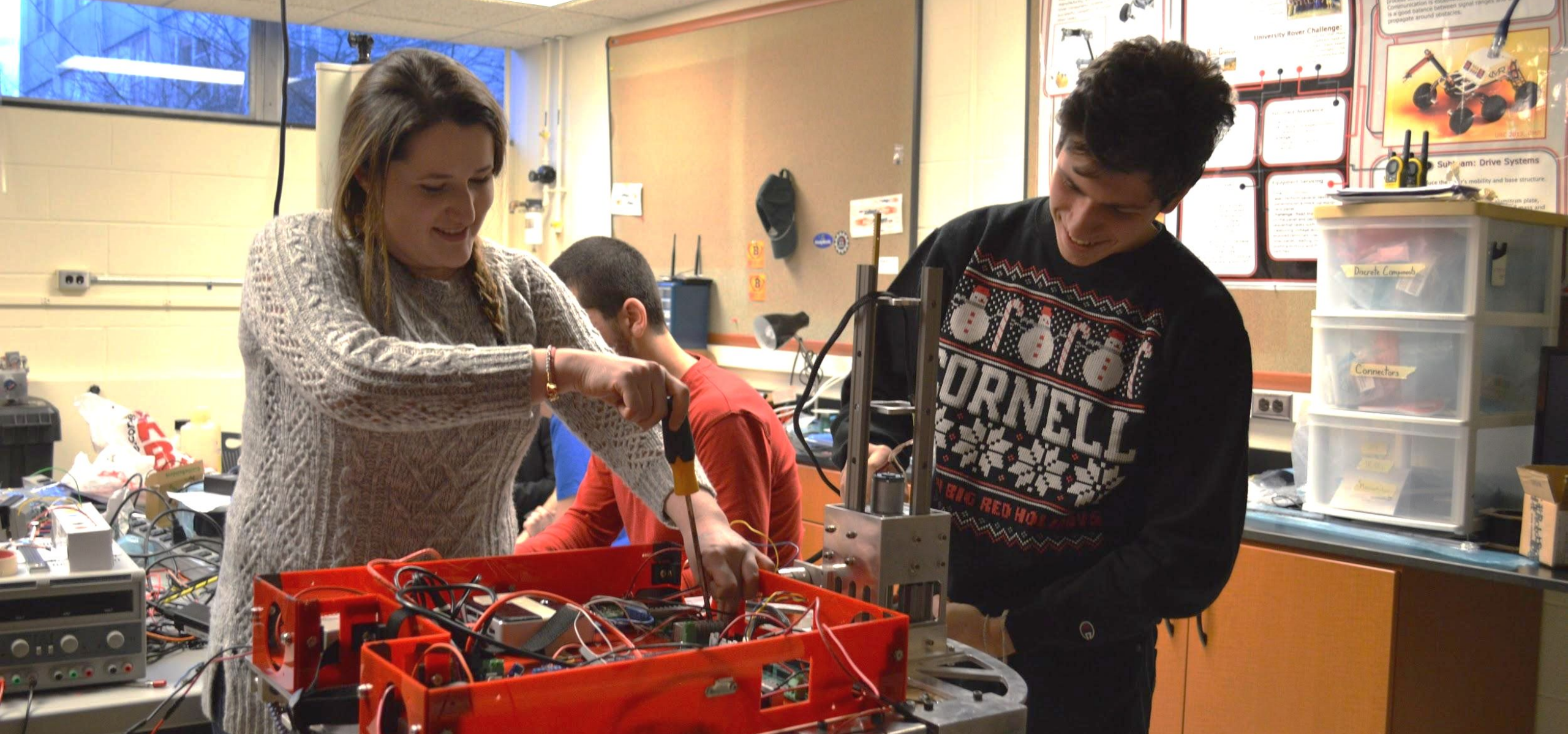


Build



Test

November – January



Hands-on Lab Work



Research

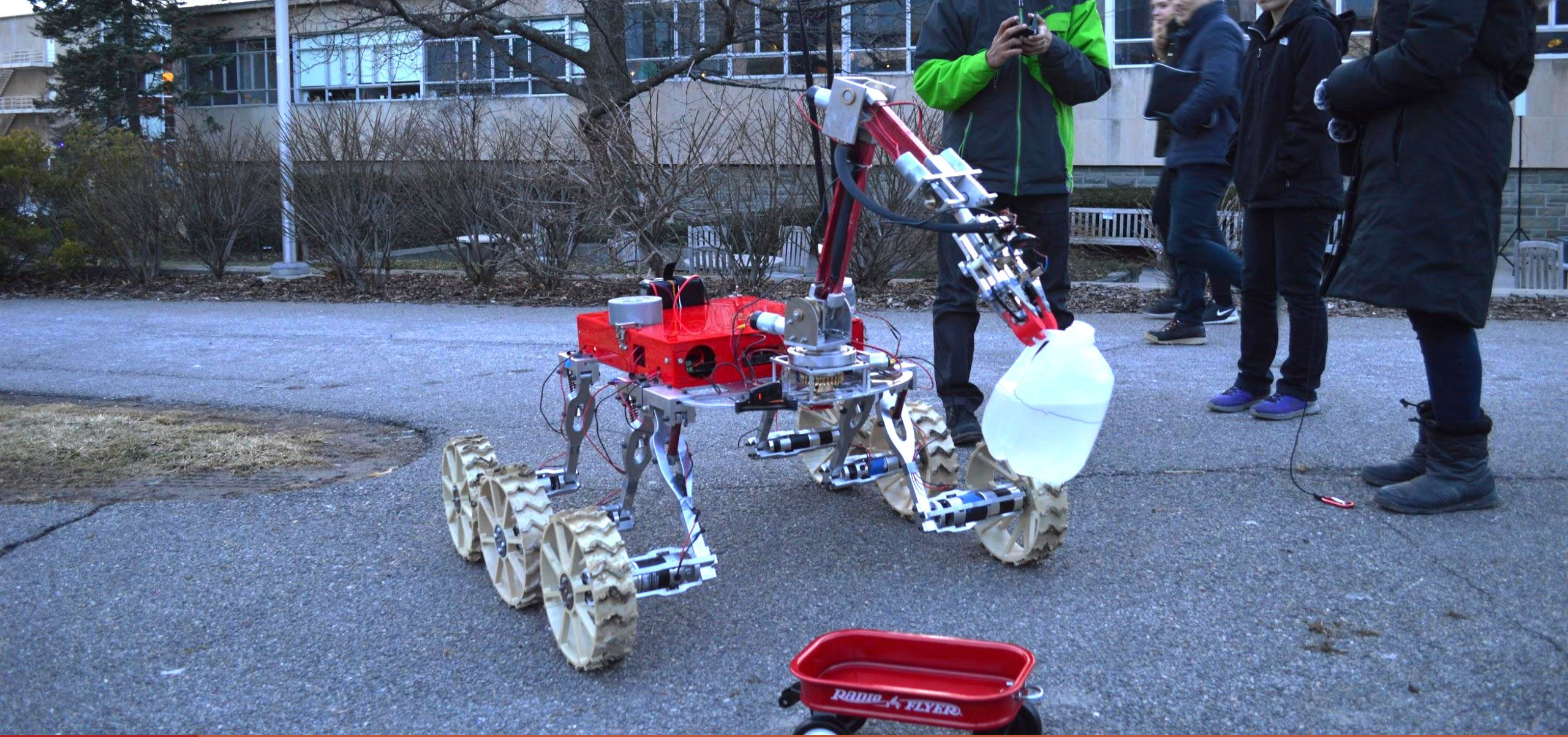


Build



Test

January – May



Testing for Competition

Opportunities

for Diverse Interests

MechE	ECE	CS	MORE +
Physics	Sensors	Data-Driven	Marketing
Computer Aided Design & Analysis	Wireless Communication	Web & Software Development	Chem, Bio, and Environmental
3D Printing	Power Systems	Open Source	Entrepreneurship
Product Design	Circuit Design	OS Design	Graphic Design

Drive Systems

Design chassis, electronics housing, suspension, and locomotion of the rover.

**Mechanical
Engineering**

Physics

Robotics

Machining

Computer Aided
Design & Analysis

Product Design

Task Systems

Develop specialized rover components for competition field tasks.

Mechanical
Engineering

Prototyping

Robotics

3D Printing

Computer Aided
Design & Analysis

Product Design

Controls Electrical

Build the Electronics Core and manage wireless communication.

Computer &
Electrical
Engineering

Sensors

Robotics

Power Systems

Wireless
Communications

Circuit Design



Controls Software

Develop C++ software for the rover's operating system.

Computer Science

Linux

Robotics

OS Design

Hardware
Abstraction Layer

Open Source

Science

Research and analyze soil samples for signs of life.

**Chemistry, Biology,
and Environmental
Engineering**

Sensors

Robotics

Geology

Cyanobacteria
Research

Spectroscopy

Business

Administer team finances, sponsorships, marketing, and technology

Computer & Information
Science

Art, Architecture, & Planning

More +

Accounting

Marketing

Data-Driven

Web Design &
App Development

Graphic Design

Our Track Record



A six-wheeled rover with a red frame and black tires is positioned in a desert landscape. The rover has a white top section with various instruments and antennas. The background features a sunset sky with orange and yellow hues, and a prominent rock formation in the distance. The ground is rocky and cracked.

GAIN hands-on experience.
LEARN from peer mentors.
GROW as a leader.

Join a passionate community!



Thank You!



Apply Online!

Deadline:
Monday, Sept 7
at 11:59pm

Learn More

marsrover.engineering.cornell.edu